



MATLAB model for gyroscope digital signal processing

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Purpose and aim

The goal of the project is to develop a MATLAB model of the digital signal processing scheme in our MEMS gyroscope system to facilitate further development and understanding.

Results, important findings

The model has shown to be able to accurately simulate the main output variables, such as applied rotational rate, excitation amplitude- and frequency.

The project is done in collaboration
with Safran Sensing Technologies
Norway (SSTN)



Supervisors: Lars Hoff (USN)
and Sverre Normann (SSTN)

